The objective is to solve numerically the following initial value problem (IVP)

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\begin{cases} y'(t) = -y(t) + e^{-t} \cos(t) , t > 0 \\ y(0) = 0 \end{cases}
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using the Euler and 4th-order Runge-Kutta methods. The exact solution is $Y(t) = e^{-t} \sin(t)$.

- 1. Write the C function *double derivative(double t, double y)* which calculates the right-hand side of the differential equation, i.e. $f(t, y) = -y + e^{-t} \cos(t)$.
- 2. Write the C function *double solution(double t, double y)* which calculates Y(t).
- 3. Write the main function which solves the IVP using the Euler method. The following parameters are to be read from the keyboard: H the time step, NS the number of time steps. This way, the integration interval is [0,NS*H]. The formula of the Euler's method is

 $y_{k+1} = y_k + H \cdot f(t_k, y_k)$, k = 0, 1, ..., NS - 1

where, in our case, $y_0 = 0$. At each step, dump the values of t_k , y_k , $Y(t_k)$ and $e_k = Y(t_k) - y_k$ to an output file on the hard disk.

- 4. Repeat calculations with (H, NS) = (0.01, 3000), (0.005, 6000) and (0.0025, 12000). Compare the error distributions on the same plot using Grapher.
- 5. Write a new version of the main function which uses the 4th order R-K method, i.e.

 $q_{1} = H \cdot f(t_{k}, y_{k})$ $q_{2} = H \cdot f(t_{k} + H/2, y_{k} + q_{1}/2)$ $q_{3} = H \cdot f(t_{k} + H/2, y_{k} + q_{2}/2)$ $q_{4} = H \cdot f(t_{k} + H, y_{k} + q_{3})$ $y_{k+1} = y_{k} + (q_{1} + 2q_{2} + 2q_{3} + q_{4})/6$

6. Repeat the calculations with three different step sizes H and the corresponding numbers of steps NS. Compare the numerical accuracy of the 4th order R-K and the Euler methods.